Challenges of state and parameter estimation in cardiac dynamics nonlinear dynamics of the heart

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Towards data assimilation in cardiac dynamics

- cardiac tissue is an excitable medium
- measuring cardiac dynamics
- mathematical models of cardiac dynamics
- simulating cardiac arrhythmias and novel defibrillation methods
- parameter estimation and data assimilation tasks
- synchronization based state and parameter estimation
- estimability analysis of state variables and parameters based on the delay coordinates map



electrical excitation waves



plane waves







chaos

simulations: P. Bittihn

Response of an excitable system to different stimuli

sub-threshold perturbation → small response

super-threshold perturbation → loop

repeated excitation with well **separated perturbations**

no excitation by a second pulse during refractory phase



B. Lindner et al. , Physics Reports 392 (2004) 321–424

Mathematical Models of Excitable Media

Simple generic system: The Barkley model

$$\frac{\partial u}{\partial t} = \frac{1}{\varepsilon} u(1-u) (u - u_{th}) + D \cdot \nabla^2 u$$

$$\frac{\partial v}{\partial t} = u - v$$

with: $u_{th} = \frac{v + b}{a}$

 $1/\epsilon$ time scale of the fast variable u

a measure for action potential duration

b/a measure for excitation threshold

D. Barkley, M. Kness, and L. S. Tuckerman, Phys. Rev. A 4, 2489 (1990) D. Barkley, Physica D 49, 6170 (1991)

http://www.scholarpedia.org/article/Barkley_model

Excitation waves (Barkley model)



simulations: P. Bittihn

refractory region (currently not excitable)

Spiral waves (Barkley model)



Spiral waves (Barkley model)



The Barkley Model in 3D

scroll waves



http://www.scholarpedia.org/article/Barkley_model

Cubic Barkley Model

$$\frac{\partial u}{\partial t} = \frac{1}{\varepsilon}u(1-u)\left(u-\frac{v+b}{a}\right) + D\cdot\nabla^2 u$$
$$\frac{\partial v}{\partial t} = u^3 - v$$

exhibits spiral break up and spatio-temporal chaos



Many excitable media exhibit transient chaos:

- lifetime of chaotic transients increases exponentially with system size
- Kaplan-Yorke dimension of the chaotic saddle increases linearly with system size and with number of phase singularities

Measuring Cardiac Dynamics

isolated hearts (in a perfusion system)

- Membrane potential and Calcium concentration on the surface using fluorescent dyes (optical mapping)
- Shape reconstruction based on 3 or more camera projections
- Electrical signals from local electrodes (ECG like)
- CT scans for determining the geometry of the heart
- Ultrasound measurements of mechanical activity and deformation

intact hearts (within the body)

- Electrical signals from the body surface (ECG imaging; inverse problem)
- CT scans for determining the geometry of the heart
- Ultrasound measurements of mechanical activity and deformation

Optical Mapping

Visualisation of membrane voltage and Ca⁺ concentration using fluorescent dyes



RISDA 2017

Optical Mapping

Isolated heart in a Langendorf perfusion system

> Visualisation of membrane voltage and Ca⁺ concentration using fluorescent dyes

> > Review: Efimov, Nikolski & Salama, Circ. Res. (2004)

Motion Artifact Reduction

Use motion tracking for separating electrical wave pattern from mechanical motion

Raw data

Motion tracking

Raw data

Stabilized data







Ventricular Tachycardia



Electrical Excitation Waves

J. Christoph, J. Schröder-Schetelig

Ventricular Fibrillation in a Pig Heart



membrane voltage (di-4-ANEPPS)

3D panoramic view using 4 cameras (128x128 px @ 500Hz)

J. Schröder-Schetelig

Mathematical Models of Cardiac Dynamics

simple qualitative models: Barkley (2), FitzHugh-Nagumo (2), Aliev-Panfilov (2), ...

generic qualitative models: Fenton-Karma (3), Beeler-Reuter (8), ...

detailed ionic models: Luo-Rudy-II (15), Majahan (27), Bondarenko (44), ...

see Scholarpedia article by F. Fenton and E. Cherry discussing 45 models of cardiac cells

$$\frac{\partial V_m}{\partial t} = \nabla \cdot \underline{\mathbf{D}} \nabla V_m - I_{\text{ion}}(V_m, \mathbf{h}) / C_m$$

$$\frac{\partial \mathbf{h}}{\partial t} = \mathbf{H}(V_m, \mathbf{h})$$

$$I_{\text{ion}}(V_m, \mathbf{h}) = \sum_x I_x(V_m, \mathbf{h}) + I_{\text{injection}}$$

local cell dynamics (15-30 variables, 150 - 300 parameters!)

Very detailed models may suffer from "overfitting" and are not very robust.

→ S.Otte et al., Commun. Nonlin. Sci. Numer. Simulat. 37, 265 (2016)

Electro-mechanical Modeling





 μCT

Segmentation & discretization

Local fiber orientation, vasculature, etc.

- Deformable Reaction-Diffusion System
- Electrophysiology (Fenton-Karma, detailed ionic model)
- Tissue mechanics (FEM, discrete particle model)
- Parameter estimation & model validation

Simulating Cardiac Arrhythmias

for Developing Novel Diagnostic and Defibrillation Approaches

Ventricular Fibrillation (VF)



J. Schröder-Schetelig

- Most common deadly manifestation of cardiac disease
- 100.000 200.000 sudden cardiac deaths (SCD) in Germany per year
- Requires immediate defibrillation using highenergy shock

Defibrillation

Principle: Reset electrical activity

external







Electric shocks: energy 360J (external) 40 J (internal) 1000 V 30 A 12 ms

Severe side effects: tissue damage - traumatic pain

G.P. Walcott et al Resuscitation 59 59-70 (2003)

Cardiac Arrhythmias

Blood vessels, scars, fatty tissue

Virtual Electrodes

- are obstacles to electrical conduction
- may act as virtual electrodes (Pumir&Krinsky, J. Theor. Biol. 199, 311 (1999))



Recruiting Virtual Electrodes for Terminating Cardiac Arrhythmias



Animation: T. Lilienkamp

Low-Energy Anti-Fibrillation Pacing (LEAP)



Membrane Potential



N = 5 low energy pulses E = 1.4 V/cm dt = 90 ms

Energy reduction: 82 %

Pulse Generator Power Amplifier

S. Luther et al., Nature 475, 235 (2011)

1 cm

Simulation using a MRT-based heart model



Parameter Estimation and Data Assimilation Tasks

- for **isolated hearts** in a Langendorf perfusion system reconstruct intramural dynamics (inside the heart) from
 - surface information employing fluorescent dyes (voltage, Ca+, mechanical stress and strain)
 - ultrasound imaging
- for **intact hearts** (inside the body)
 - reconstruct dynamics of the heart
 - electrical wave pattern using extra corporal electrodes
 (on the surface of the body) → ECG imaging (Y. Rudy, 1999)
 - mechanical deformation and motion from ultrasound imaging
- for improving simulation models
 - parameter estimation for cardiac cell models
 - model evaluation

Synchronization based state and parameter estimation

- drive the model with the time series using a suitable coupling term
- minimize synchronization error by adjusting parameters

Experiment or Model
$$s = h(x)$$
(Computer) Model $\dot{x} = f(x, p)$ $\dot{y} = f(y, q) + c(s - h(y))$

$$q \to p \quad \Rightarrow \lim_{t \to \infty} \|x(t) - y(t)\| = 0$$

U. Parlitz *et al.*, Phys. Rev. E 54, 6253 (1996) U. Parlitz, Phys. Rev. Lett. 76, 1232 (1996) D. Rey et al. Phys. Lett. A 378, 869 (2014)D. Rey et al. Phys. Rev. E 90, 062916 (2014)

Example: Excitable Media

$$\begin{array}{lll} \text{cubic Barkley model} & \frac{\partial u}{\partial t} & = & \frac{1}{\varepsilon}u(1-u)\left(u-\frac{v+b}{a}\right) + D \cdot \nabla^2 u \\ a = 0.75 \ b = 0.08 \ \varepsilon = \frac{1}{12} & \frac{\partial v}{\partial t} & = & u^3 - v \end{array}$$

$$\begin{array}{lll} \text{chaotic} & \frac{\partial v}{\partial t} & = & u^3 - v \end{array}$$

- no-flux boundary conditions
- implementation of the PDE integration scheme on a graphics processing unit (GPU) resulting in a speed up of a factor 50-100

Uni-directional local coupling "experiment" → "model" using sensors and controllers

S. Berg et al., Chaos 21, 033104 (2011) M.J. Hoffman et al., Chaos 26, 013107 (2016)





grid of size: 294×294 - sensor sizes: 6×6 grid points - sensor spacing 3 grid points

Synchronization Based State and Parameter Estimation

Typical noisy chaotic sensor signal (SNR= 12dB)

Parameter space of the response Barkley system with contour curves showing the averaged synchronization error

a) sensor value 0.0 0.0 5 10 15 20 0 b) periodic chaotic 10^{-1} 10^{-2} $avg(\Delta^2)$ 10⁻³ 10⁻⁴ 10^{-5} 0.10 1.0025 0.005 0.08 0.00. 0.00005 0.005 0.06 b 0.001 0.04 0.001 0.00_{I} 0.0025 0.02 0.00 0.6 0.8 1.0 0.8 0.6 1.0 $\boldsymbol{\mathcal{C}}$ \mathcal{C} true values S. Berg et al., Chaos **21**(3), 033104 (2011)



Model 2

Model 1

Model 3



model parameter space with contour lines of the synchronization error

drive			response		
S _{1,1}	$S_{2,1}$	S _{3,1}	<i>C</i> _{1,1}	<i>C</i> _{2,1}	C _{3,1}
spacing			spacing		
$S_{1,2}$	S _{2,2}	S _{3,2}	$\overset{C_{1,2}}{\longleftrightarrow}$	C _{2,2}	C _{3,2}
S _{1,3}	S _{2,3}	S _{3,3}	C _{1,3}	<i>C</i> _{2,3}	C _{3,3}

Synchronization Based State and Parameter Estimation

Cardiac Cell Culture Experiment drives Barkley Model



T.K. Shajahan S. Berg Estimability analysis of state variables and parameters based on delay coordinates map

Example: Colpitts Oscillator

nonlinear electronic oscillator model equations

 $\dot{x}_1 = p_1 x_2$ $\dot{x}_2 = -p_2(x_1 + x_3) - p_3 x_2$ $\dot{x}_3 = p_4 \left(x_2 + 1 - e^{-x_1} \right)$



twin-experiment: simulated data (first model variable) measurement function $h(\mathbf{x}) = x_1$

optimization (4D-Var)

J. Schumann-Bischoff and U. Parlitz, Phys. Rev. E 84, 056214 (2011)

Estimability

Example: Colpitts Oscillator



measured time series is successfully reproduced

 p_2

0.00016

 p_3

0.700

 p_1

5573

result of estimation



estim.

data

 p_4

Estimability





Success in parameter and state variable estimation depends on

- measured variable (observable)
- particular variable or parameter to be estimated

Which variables or parameters of a given model can be estimated using a given time series (observable) ?

→ Observability / Identifiability / Estimability

Investigating Estimability Using Delay Coordinates

M-dimensional discrete system $\mathbf{x}(n+1) = \mathbf{g}(\mathbf{x}(n))$

times series $\{s(n)\}$ with $s(n) = h(\mathbf{x}(n))$ $(n = 1, \dots, N)$

D-dimensional delay coordinates



delay coordinates map $G: \mathbb{R}^M \to \mathbb{R}^D$

Estimability

delay coordinates map $G: \mathbb{R}^M \to \mathbb{R}^D$



State variables x_i can be recovered from the observed time series s if the delay coordinates map G can be locally inverted, i.e. if the

Jacobian matrix $DG(\mathbf{x})$ of G has full rank

i.e., if its null space (kernel) is zero dimensional.

U. Parlitz et al., Phys. Rev. E 89, 050902(R) (2014); Chaos 24, 024411 (2014)

Estimability



 $DG^{-1}(\mathbf{y})$ maps perturbations of \mathbf{y} in delay reconstruction space to deviations from the state \mathbf{x}

uncertainty of variable x_m

$$\nu_m = \sqrt{\left[DG^{tr} \cdot DG\right]_{mm}^{-1}} = \sqrt{\left[V \cdot S^{-2} \cdot V^{tr}\right]_{mm}}$$

Detecting estimable and redundant parameters

unknown quantities $\mathbf{w} = (\mathbf{x}, \mathbf{p})$

delay coordinates map

 $\mathbf{g} = G[\mathbf{w}] = \begin{bmatrix} x_1(t), & x_1(t+\tau), & \dots, & x_1(t+(K-1)\tau) \end{bmatrix}^{tr}$

transformation of perturbations $DG \Delta w = \Delta g$

perturbations of w = (x,p) within the null space $DG\Delta w = 0$ of DG have no impact on the observations

Vanishing components of basis vectors of the null space indicate estimable parameters and (groups of) redundant parameters and variables.

Schumann-Bischoff et al., Phys. Rev. E 94, 032221 (2016)

Summary

Data Assimilation and Parameter Estimation in Cardiac Dynamics



mathematical model

parameter estimation model evaluation local cell dynamics + diffusion electro-mechanical coupling mechanical motion

synchronization estimability

Achnowledgement

Stefan Luther,

Thomas Lilienkamp, Johannes Schröder-Schetelig, Jan Schumann-Bischoff, Philip Bittihn,

and all members of the Research Group Biomedical Physics at the

Max Planck Institute for Dynamics and Self-Organization, Göttingen

